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Search results, Notes. The estimated image is design as the posterior mean of a probability law (from a Bayesian analysis).

The mean is defined as a sum over all the possible images weighted by their respective probability., [OpenCV](#) [Change](#) [Logs](#)

version:3.4.2. July, 2018. OpenCV 3.4.2 has been released, with further extended dnn module, documentation improvements, some other new functionality and bug fixes.

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